



Four-Dimensional Algebras A_4 With Radical $R(A_4)$ Of Dimension 0 And 1"

Tanirbergenov Sadyk Aleuovich

Associate Professor of the Department of Mathematics
Ajiniyaz Nukus State Pedagogical Institute

ABSTRACT

The structure constants of the algebra A_4 define, in four-dimensional affine space, a system of curvilinear coordinates with constant connection coefficients. The study of curvilinear coordinates with constant connection coefficients is related to the study and classification of commutative and associative algebras A_4 . Therefore, this work considers the classification of commutative and associative algebras A_4 with radical $R(A_4)$ of dimension 0 and 1.

Keywords:

Algebra, commutativity, associativity, radical, real numbers, ideal, simple, semisimple, basis.

The theory of commutative and associative algebras is a well-developed branch of algebra. At the same time, in many problems of geometry, it becomes necessary to use certain concepts from linear algebra [1]. Therefore, the problem of classifying the entire set of associative and commutative algebras is of particular interest. In the present work, this problem is solved for four-dimensional algebras with a radical $R(A_4)$ of dimension 0 and 1.

In the classification of four-dimensional algebras over the field of real numbers, well-known theorems of linear algebra are used [2], [3].

Theorem 1. If a commutative and associative algebra A is semisimple, then it decomposes into a direct sum of a certain number of algebras of complex numbers \mathbf{C} and real numbers \mathbf{R} .

Theorem 2. If $R(A)$ is the radical of an associative algebra A , then the factor algebra $A/R(A)$ is semisimple.

Theorem 3. In an arbitrary associative algebra A there exists a semisimple subalgebra U complementary to the maximal nilpotent ideal $R(A)$.

Let C_{ij}^k – be the structure constants of the algebra A . The multiplication law of the basis vectors ε_k in the algebra A is given by the formula:

$$\varepsilon_i \varepsilon_j = C_{ij}^k \varepsilon_k. \quad (1)$$

The conditions of commutativity and associativity of algebra A are respectively equivalent to the identities

$$C_{ij}^k = C_{ji}^k, \quad C_{ij}^m C_{mk}^s = C_{jk}^m C_{mi}^s$$

which these structural constants satisfy. These relations are equivalent to the relations

$$\varepsilon_i \varepsilon_j = \varepsilon_j \varepsilon_i, \quad (\varepsilon_i \varepsilon_j) \varepsilon_k = \varepsilon_i (\varepsilon_j \varepsilon_k). \quad (2)$$

Let's consider a four-dimensional commutative and associative algebra A_4 with basis $\{\varepsilon_1, \varepsilon_2, \varepsilon_3, \varepsilon_4\}$. If the algebra A_4 is semisimple, then this algebra does not have a radical of dimension different from zero. Therefore, for a semisimple algebra, $\dim R(A_4) = 0$ and there are three possible cases:

$$\text{I. } A_4 = C \oplus C; \quad \text{II. } A_4 = C \oplus R \oplus R; \quad \text{III.}$$

$$A_4 = R \oplus R \oplus R \oplus R.$$

The multiplication tables of the basis vectors of these algebras are respectively written in the form:

$$\mathcal{E}_1 \mathcal{E}_1 = \mathcal{E}_1, \mathcal{E}_1 \mathcal{E}_2 = \mathcal{E}_2 \mathcal{E}_1 = \mathcal{E}_2, \mathcal{E}_1 \mathcal{E}_3 = \mathcal{E}_3 \mathcal{E}_1 = 0, \mathcal{E}_1 \mathcal{E}_4 = \mathcal{E}_4 \mathcal{E}_1 = 0,$$

$$\text{I)} \quad \mathcal{E}_2 \mathcal{E}_2 = -\mathcal{E}_1, \mathcal{E}_2 \mathcal{E}_3 = \mathcal{E}_3 \mathcal{E}_2 = 0, \mathcal{E}_2 \mathcal{E}_4 = \mathcal{E}_4 \mathcal{E}_2 = 0,$$

$$\mathcal{E}_3 \mathcal{E}_3 = \mathcal{E}_3, \mathcal{E}_3 \mathcal{E}_4 = \mathcal{E}_4 \mathcal{E}_3 = \mathcal{E}_4, \mathcal{E}_4 \mathcal{E}_4 = -\mathcal{E}_3.$$

$$\mathcal{E}_1 \mathcal{E}_1 = \mathcal{E}_1, \mathcal{E}_1 \mathcal{E}_2 = \mathcal{E}_2 \mathcal{E}_1 = \mathcal{E}_2, \mathcal{E}_1 \mathcal{E}_3 = \mathcal{E}_3 \mathcal{E}_1 = 0, \mathcal{E}_1 \mathcal{E}_4 = \mathcal{E}_4 \mathcal{E}_1 = 0,$$

$$\text{II)} \quad \mathcal{E}_2 \mathcal{E}_2 = -\mathcal{E}_1, \mathcal{E}_2 \mathcal{E}_3 = \mathcal{E}_3 \mathcal{E}_2 = 0, \mathcal{E}_2 \mathcal{E}_4 = \mathcal{E}_4 \mathcal{E}_2 = 0,$$

$$\mathcal{E}_3 \mathcal{E}_3 = \mathcal{E}_3, \mathcal{E}_3 \mathcal{E}_4 = \mathcal{E}_4 \mathcal{E}_3 = 0, \mathcal{E}_4 \mathcal{E}_4 = \mathcal{E}_4.$$

$$\mathcal{E}_1 \mathcal{E}_1 = \mathcal{E}_1, \mathcal{E}_1 \mathcal{E}_2 = \mathcal{E}_2 \mathcal{E}_1 = \mathcal{E}_1 \mathcal{E}_3 = \mathcal{E}_3 \mathcal{E}_1 = \mathcal{E}_1 \mathcal{E}_4 = \mathcal{E}_4 \mathcal{E}_1 = 0, \mathcal{E}_2 \mathcal{E}_2 = \mathcal{E}_2,$$

$$\text{III)} \quad \mathcal{E}_2 \mathcal{E}_3 = \mathcal{E}_3 \mathcal{E}_2 = \mathcal{E}_2 \mathcal{E}_4 = \mathcal{E}_4 \mathcal{E}_2 = 0, \mathcal{E}_3 \mathcal{E}_3 = \mathcal{E}_3, \mathcal{E}_3 \mathcal{E}_4 = \mathcal{E}_4 \mathcal{E}_3 = 0, \mathcal{E}_4 \mathcal{E}_4 = \mathcal{E}_4.$$

Using formula (1), the structure constants of the above-mentioned algebras I-III are determined.

The structure constants for an algebra of type I are defined as:

$$\mathcal{E}_1 = \mathcal{E}_1 \mathcal{E}_1 = C_{11}^1 \mathcal{E}_1 + C_{11}^2 \mathcal{E}_2 + C_{11}^3 \mathcal{E}_3 + C_{11}^4 \mathcal{E}_4 \Rightarrow C_{11}^1 = 1, C_{11}^2 = C_{11}^3 = C_{11}^4 = 0,$$

$$\mathcal{E}_1 \mathcal{E}_2 = \mathcal{E}_2 \mathcal{E}_1 = \mathcal{E}_2 \Rightarrow C_{12}^2 = C_{21}^2 = 1, C_{12}^1 = C_{21}^1 = C_{12}^3 = C_{21}^3 = C_{12}^4 = C_{21}^4 = 0,$$

$$\mathcal{E}_1 \mathcal{E}_3 = \mathcal{E}_3 \mathcal{E}_1 = 0 \Rightarrow C_{13}^1 = C_{31}^1 = C_{13}^2 = C_{31}^2 = C_{13}^3 = C_{31}^3 = C_{13}^4 = C_{31}^4 = 0,$$

$$\mathcal{E}_1 \mathcal{E}_4 = \mathcal{E}_4 \mathcal{E}_1 = 0 \Rightarrow C_{14}^1 = C_{41}^1 = C_{14}^2 = C_{41}^2 = C_{14}^3 = C_{41}^3 = C_{14}^4 = C_{41}^4 = 0,$$

$$\mathcal{E}_2 \mathcal{E}_2 = -\mathcal{E}_1 \Rightarrow C_{22}^1 = -1, C_{22}^2 = C_{22}^3 = C_{22}^4 = 0,$$

$$\mathcal{E}_2 \mathcal{E}_3 = \mathcal{E}_3 \mathcal{E}_2 = 0 \Rightarrow C_{23}^1 = C_{32}^1 = C_{23}^2 = C_{32}^2 = C_{23}^3 = C_{32}^3 = C_{23}^4 = C_{32}^4 = 0,$$

$$\mathcal{E}_3 \mathcal{E}_3 = \mathcal{E}_3 \Rightarrow C_{33}^3 = 1, C_{33}^1 = C_{33}^2 = C_{33}^4 = 0,$$

$$\mathcal{E}_3 \mathcal{E}_4 = \mathcal{E}_4 \mathcal{E}_3 = \mathcal{E}_4 \Rightarrow C_{34}^4 = C_{43}^4 = 1, C_{34}^1 = C_{43}^1 = C_{34}^2 = C_{43}^2 = C_{34}^3 = C_{43}^3 = 0,$$

$$\mathcal{E}_4 \mathcal{E}_4 = -\mathcal{E}_3 \Rightarrow C_{44}^3 = -1, C_{44}^1 = C_{44}^2 = C_{44}^4 = 0.$$

Similarly, for algebra II, the structure constants have the form:

$$C_{ij}^1 = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & -1 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix}, \quad C_{ij}^2 = \begin{pmatrix} 0 & 1 & 0 & 0 \\ 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix},$$

$$C_{ij}^3 = \begin{pmatrix} 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix}, \quad C_{ij}^4 = \begin{pmatrix} 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}.$$

The structure constants of an algebra of type III are written in the form:

$$C_{ij}^1 = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix}, \quad C_{ij}^2 = \begin{pmatrix} 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix},$$

$$C_{ij}^3 = \begin{pmatrix} 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix}, \quad C_{ij}^4 = \begin{pmatrix} 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}.$$

If the algebra A_4 is not semisimple, then there exists a non-zero radical $R(A_4)$.

Let $\dim R(A_4)=1$ и ε_4 – be a basis element in the radical $R(A_4)$. Then, according to Theorem 2, the factor algebra $A_4/R(A_4)$ will be a three-dimensional semisimple algebra.

Hence, the following two cases are possible:

1. In the case $A_4 / R(A_4) = C \oplus R$, according to Theorem 3, the multiplication law of the basis elements $\varepsilon_1, \varepsilon_2, \varepsilon_3, \varepsilon_4$ in the algebra A_4 is given by:

$$\begin{aligned} \varepsilon_1\varepsilon_1 &= \varepsilon_1, \quad \varepsilon_1\varepsilon_2 = \varepsilon_2\varepsilon_1 = \varepsilon_2, \quad \varepsilon_1\varepsilon_3 = \varepsilon_3\varepsilon_1 = 0, \quad \varepsilon_1\varepsilon_4 = \varepsilon_4\varepsilon_1 = \lambda\varepsilon_4, \\ \varepsilon_2\varepsilon_2 &= -\varepsilon_1, \quad \varepsilon_2\varepsilon_3 = \varepsilon_3\varepsilon_2 = 0, \quad \varepsilon_2\varepsilon_4 = \varepsilon_4\varepsilon_2 = \mu\varepsilon_4, \\ \varepsilon_3\varepsilon_3 &= \varepsilon_3, \quad \varepsilon_3\varepsilon_4 = \varepsilon_4\varepsilon_3 = \nu\varepsilon_4, \quad \varepsilon_4\varepsilon_4 = 0, \end{aligned} \quad (3)$$

where is $\lambda, \mu, \nu \in R$.

From the associativity condition (2) of the algebra A_4 , we obtain the following systems of equations:

$$\lambda = \lambda^2, \quad \lambda = -\mu^2, \quad \nu = \nu^2, \quad \mu = \lambda\mu, \quad \lambda\nu = 0, \quad \mu\nu = 0.$$

The solution to this system of equations is:

$$\begin{cases} \lambda = 0, \\ \mu = 0, \\ \nu = 0 \end{cases} \quad \text{или} \quad \begin{cases} \lambda = 0, \\ \mu = 0, \\ \nu = 1. \end{cases}$$

At the same time, for the first case expression (3) is written in the form,

$$\begin{aligned} \varepsilon_1\varepsilon_1 &= \varepsilon_1, \quad \varepsilon_1\varepsilon_2 = \varepsilon_2\varepsilon_1 = \varepsilon_2, \quad \varepsilon_1\varepsilon_3 = \varepsilon_3\varepsilon_1 = \varepsilon_1\varepsilon_4 = \varepsilon_4\varepsilon_1 = 0, \\ \varepsilon_2\varepsilon_2 &= -\varepsilon_1, \quad \varepsilon_2\varepsilon_3 = \varepsilon_3\varepsilon_2 = \varepsilon_2\varepsilon_4 = \varepsilon_4\varepsilon_2 = 0, \\ \varepsilon_3\varepsilon_3 &= \varepsilon_3, \quad \varepsilon_3\varepsilon_4 = \varepsilon_4\varepsilon_3 = \varepsilon_4\varepsilon_4 = 0, \end{aligned} \quad (4)$$

and for the second case,

$$\begin{aligned} \varepsilon_1\varepsilon_1 &= \varepsilon_1, \quad \varepsilon_1\varepsilon_2 = \varepsilon_2\varepsilon_1 = \varepsilon_2, \quad \varepsilon_1\varepsilon_3 = \varepsilon_3\varepsilon_1 = \varepsilon_1\varepsilon_4 = \varepsilon_4\varepsilon_1 = 0, \\ \varepsilon_2\varepsilon_2 &= -\varepsilon_1, \quad \varepsilon_2\varepsilon_3 = \varepsilon_3\varepsilon_2 = \varepsilon_2\varepsilon_4 = \varepsilon_4\varepsilon_2 = 0, \\ \varepsilon_3\varepsilon_3 &= \varepsilon_3, \quad \varepsilon_3\varepsilon_4 = \varepsilon_4\varepsilon_3 = \varepsilon_4, \quad \varepsilon_4\varepsilon_4 = 0. \end{aligned} \quad (5)$$

An algebra whose multiplication law of the basis elements is given in the form (4) is called an algebra of type IV. Similarly, an algebra of type V is defined by relations (5).

The structure constants of the algebra of type IV have the form:

$$C_{ij}^1 = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & -1 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix}, \quad C_{ij}^2 = \begin{pmatrix} 0 & 1 & 0 & 0 \\ 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix},$$

$$C_{ij}^3 = \begin{pmatrix} 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix}, \quad C_{ij}^4 = \begin{pmatrix} 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix},$$

and for the type V,

$$C_{ij}^1 = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & -1 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix}, \quad C_{ij}^2 = \begin{pmatrix} 0 & 1 & 0 & 0 \\ 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix},$$

$$C_{ij}^3 = \begin{pmatrix} 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix}, \quad C_{ij}^4 = \begin{pmatrix} 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 1 & 0 \end{pmatrix}.$$

2. For this case $A_4 / R(A_4) = R \oplus R \oplus R$ we write the multiplication law of the basis elements of the algebra as A_4 :

$$\begin{aligned} \varepsilon_1 \varepsilon_1 &= \varepsilon_1, \quad \varepsilon_1 \varepsilon_2 = \varepsilon_2 \varepsilon_1 = \varepsilon_1 \varepsilon_3 = \varepsilon_3 \varepsilon_1 = 0, \quad \varepsilon_1 \varepsilon_4 = \varepsilon_4 \varepsilon_1 = \lambda \varepsilon_4, \\ \varepsilon_2 \varepsilon_2 &= \varepsilon_2, \quad \varepsilon_2 \varepsilon_3 = \varepsilon_3 \varepsilon_2 = 0, \quad \varepsilon_2 \varepsilon_4 = \varepsilon_4 \varepsilon_2 = \mu \varepsilon_4, \\ \varepsilon_3 \varepsilon_3 &= \varepsilon_3, \quad \varepsilon_3 \varepsilon_4 = \varepsilon_4 \varepsilon_3 = \nu \varepsilon_4, \quad \varepsilon_4 \varepsilon_4 = 0. \end{aligned} \quad (6)$$

From the associativity conditions of the algebra A_4 , we obtain the following systems of equations:

$$\begin{cases} \lambda = \lambda^2, \quad \mu = \mu^2, \quad \nu = \nu^2, \\ \lambda \mu = 0, \quad \lambda \nu = 0, \quad \nu \mu = 0. \end{cases}$$

This system of equations has the following solutions:

- 2.1) $\lambda = 1 \Rightarrow \mu = \nu = 0$;
- 2.2) $\mu = 1 \Rightarrow \lambda = \nu = 0$;
- 2.3) $\nu = 1 \Rightarrow \lambda = \mu = 0$;
- 2.4) $\lambda = 0, \mu = 0, \nu = 0$.

The multiplication table (6) of the basis elements of the algebra in case (2.1) is written in the form:

	ε_1	ε_2	ε_3	ε_4
ε_1	ε_1	0	0	ε_4
ε_2	0	ε_2	0	0
ε_3	0	0	ε_3	0
ε_4	ε_4	0	0	0

(7)

In case (2.2), after substituting the basis elements according to the formulas:

$$\bar{\varepsilon}_1 = \varepsilon_2, \quad \bar{\varepsilon}_2 = \varepsilon_1, \quad \bar{\varepsilon}_3 = \varepsilon_3, \quad \bar{\varepsilon}_4 = \varepsilon_4$$

...once again transforms the multiplication law (6) into table (7). Similarly, in case (2.3), after substituting the basis elements:

$$\bar{\varepsilon}_1 = \varepsilon_3, \quad \bar{\varepsilon}_2 = \varepsilon_2, \quad \bar{\varepsilon}_3 = \varepsilon_1, \quad \bar{\varepsilon}_4 = \varepsilon_4$$

...the multiplication law (6) is again reduced to table (7). In case (2.4), the multiplication law (6) is rewritten as follows:

	ε_1	ε_2	ε_3	ε_4	
ε_1	ε_1	0	0	0	(8)
ε_2	0	ε_2	0	0	
ε_3	0	0	ε_3	0	
ε_4	0	0	0	0	

Thus, the following theorem holds.

Theorem. There exist seven pairwise non-isomorphic four-dimensional commutative and associative algebras with a radical of dimension 0 and 1.

Used literature

1. Tanirbergenov, S. A. (2023, May 2–3). Flat affine connections on a manifold with constant coefficients Γ_{jk}^i . In International Scientific and Practical

Conference “Topical Problems of Mathematical Modeling and Information Technologies” (Vol. 1, pp. 81–82). Nukus. (in Russian).

2. Chebotarev, N. G. (1949). Introduction to the theory of algebras. Moscow-Leningrad: Gostekhizdat. (in Russian).
3. Kantor, I. L., & Solodovnikov, A. S. (1973). Hypercomplex numbers. Moscow: Nauka. (in Russian).