

Introduction.

The main method of cultivating agricultural crops in Central Asia is artificial irrigation. The development of irrigated agriculture is limited by water resources, hence great attention is paid to the wide use of groundwater, which is an internal reserve.

usage

Mathematical Model. A mathematical model is formulated in the strict terms of mathematical language, and assumptions (laws, limitations, etc.) that are made when modeling a real process are stipulated, because it is impractical to consider all factors determining the aspects of the phenomenon at once. For example, unsteady filtration of groundwater in heterogeneous layers can be modeled as a flow in a multilayer layer, in which interlayer transfers are considered based on the Myatiev-Girinsky hypothesis. According to such an assumption, the flow of water in a

Volume 25| December 2023 ISSN: 2795-7667

heterogeneous layer is described by a system of partial differential equations. These equations are accompanied by additional conditions at wells, horizontal drains, the boundary of the filtration area, etc., characterizing the regime of operation of the aquifer (initial and boundary conditions).

Material And Methods.

Unsteady Filtration of Groundwater. Consider unsteady filtration of groundwater in a heterogeneous filtration area G with an arbitrary boundary Γ. Here we will take into account infiltration, evaporation, operation of vertical and horizontal drains, and other hydraulic and reclamation structures. Suppose the layer through which water moves is underlain by a horizontal aquiclude. Then, assuming that the level of the free surface is measured from the aquiclude and changes little over the entire extent of the layer, such a process will be described by the following quasilinear partial differential equation of the parabolic type:

Consider the mathematical model of unsteady groundwater filtration in a heterogeneous layer.

$$
\mu \frac{\partial H}{\partial t} = \frac{\partial}{\partial x} \left(k_b (H \frac{\partial H}{\partial x}) + f - w \right) \tag{1}
$$

 $H(x,t) = H_{H}(x), t = 0$ (2)

$$
\left. \frac{\partial H}{\partial x} \right|_{x=0} = 0 \tag{3}
$$

$$
\left. \frac{\partial H}{\partial x} \right|_{x=L} = 0 \tag{4}
$$

where $H(x,t)$ is the level of groundwater from the aquiclude to the free surface;

 $u-$ free water discharge or lack of saturation

 $K(x)$ - is the filtration coefficient;

 $f(x,t)$, $W(x,t)$ - are the functions of infiltration and evaporation;

x - are horizontal coordinates.

Let's focus on the free term W. Numerous field observations show that evaporation depends on the depth of the groundwater. M.M. Krylov and S.F. Averyanov suggest that the formula for evaporation is valid:

$$
W = \begin{cases} W_0 \left(\frac{H - H_{kp}}{m_B - H_{kp}} \right)^n; H > H_{kp} \\ 0; \qquad H \le H_{kp} \end{cases} \tag{5}
$$

where W_0 - is the evaporation from the daily surface;

 H_{kp}^{\parallel} is the critical depth;

n - is a parameter.

We still consider wells as point sources or sinks. Solve the boundary problem (1) - (4) using the finite difference method. First, in (1) - (4) we go
to dimensionless variables
 $H^* = \frac{H}{H_s}; \qquad K_B^* = \frac{K_B}{K_s}; \qquad x^* = \frac{x}{L};$ to dimensionless variables

sionless variables
\n
$$
H^* = \frac{H}{H_0}; \qquad K_B^* = \frac{K_B}{K_0}; \qquad x^* = \frac{x}{L};
$$
\n
$$
\tau = \frac{K_0 H_0 t}{\mu L^2}; \qquad f^* = \frac{2L^2}{K_0 H_0^2} f; \qquad W^* = \frac{2L^2}{K_0 H_0^2} W
$$

and get the following dimensionless problem:

$$
\frac{\partial H^2}{H \partial \tau} = \frac{\partial}{\partial x} (K_B \frac{\partial H^2}{\partial x}) + f - w \tag{6}
$$

$$
H(x,t) = H_{H}(x), \ t = 0 \tag{7}
$$

$$
\left. \frac{\partial H}{\partial x} \right|_{x=0} = 0 \tag{8}
$$

$$
\left. \frac{\partial H}{\partial x} \right|_{x=L} = 0 \tag{9}
$$

Results.

Approximate the differential operators of equation (6) with their finite-difference analogs

on the grid.
 $\frac{\Delta x^2 H_i^{l+1}}{\Delta \tau} - \frac{\Delta x^2 H_i^{l}}{\Delta \tau} = K_{b i-0.5} 2 \tilde{H}_{i-1}^{(l+1)} H_{i-1}^{(l+1)} + K_{b i-0.5} \tilde{H}_{i-1}^{(2l+1)} - 4(K_{b i-0.5} + K_{b i+0.5}) \tilde{H}_i^{(l+1)} H_i^{(l+1)} +$

equation (b) with their finite-entire enter since and
$$
\frac{\Delta x^2 H_i^{l+1}}{\Delta \tau} - \frac{\Delta x^2 H_i^{l}}{\Delta \tau} = K_{bi-0.5} 2 \tilde{H}_{i-1}^{(l+1)} H_{i-1}^{(l+1)} + K_{bi-0.5} \tilde{H}_{i-1}^{2(l+1)} - 4(K_{bi-0.5} + K_{bi+0.5}) \tilde{H}_i^{(l+1)} H_i^{(l+1)} +
$$

$$
+ 2(K_{bi-0.5} + K_{bi+0.5}) \tilde{H}_i^{2(l+1)} + K_{bi+0.5} 2 \tilde{H}_{i+1}^{(l+1)} H_{i+1}^{(l+1)} - K_{bi+0.5} \tilde{H}_i^{2(l+1)} + \Delta x^2 f - \Delta x^2 w
$$
(11)

From this, we get:

$$
a_i H_{i-1} - b_i H_i + c_i H_{i+1} = -d_i \tag{12}
$$

where

$$
\begin{split}\n&\alpha_i = K_{bi-0.5} 2\tilde{H}_{i-1}^{(i+1)}, \quad b_i = \frac{\Delta x^2}{\Delta \tau} - 4(K_{bi-0.5} + K_{bi+0.5})\tilde{H}_i^{(i+1)}, \quad c_i = K_{bi+0.5} 2\tilde{H}_{i+1}^{(i+1)}, \\
&- d_i = -(K_{bi-0.5}\tilde{H}_{i-1}^{2(i+1)} + 2(K_{bi-0.5} + K_{bi+0.5})\tilde{H}_i^{2(i+1)} - K_{bi+0.5}\tilde{H}_{i+1}^{2(i+1)} + \Delta x^2 f - \Delta x^2 w - \frac{\Delta x^2 H_i^{i+1}}{\Delta \tau}\n\end{split}
$$

the finite difference equation, nonlinear with respect to the square of the desired function. To solve it, we apply the method of quasilinearization [9], according to which the nonlinear term φ (H) is represented as

$$
\varphi(H) \Box \varphi(\tilde{H}) + (H^2 - \tilde{H}^2) \frac{\partial \varphi}{\partial H^2}(\tilde{H}). \tag{13}
$$

where $\tilde{H} = H_{i,k+1}^{(s)}$; **s** - is the iteration number. In this case $H^{(0)}_{i,k+1} = H_{i,k}$

The iterative process continues until the condition is met

$$
\max_{i} \left| H_i^{(s)} - H_i^{(s+1)} \right| \le \varepsilon \tag{14}
$$

() *specified small value* −

To find each of the successive approximations, it is necessary to solve the linear finite difference equation of the form (12), the method of solving which was considered in the literature. [1] We found the shooting coefficients Ai, Bi.

$$
\begin{cases}\na_{i}H_{i-1}-b_{i}H_{i}+c_{i}H_{i+1}=d_{i} \\
H_{i-1}=A_{i-1}H_{i}+B_{i-1} \\
a_{i}(A_{i-1}H_{i}+B_{i-1})-b_{i}H_{i}+c_{i}H_{i+1}=-d_{i} \\
a_{i}A_{i-1}H_{i}+a_{i}B_{i-1}-b_{i}H_{i}+c_{i}H_{i+1}=-d_{i} \\
(a_{i}A_{i-1}-b_{i})H_{i}+c_{i}H_{i+1}=-d_{i}-a_{i}B_{i-1} \\
(a_{i}A_{i-1}-b_{i})H_{i}=-\left(d_{i}+a_{i}B_{i-1}\right)-c_{i}H_{i+1}\n\end{cases}
$$

$$
H_{i} = -\frac{(d_{i} + a_{i}B_{i-1})}{a_{i}A_{i-1} - b_{i}} - \frac{c_{i}H_{i+1}}{a_{i}A_{i-1} - b_{i}}
$$

\n
$$
H_{i} = \frac{(d_{i} + a_{i}B_{i-1})}{b_{i} - a_{i}A_{i-1}} + \frac{c_{i}H_{i+1}}{b_{i} - a_{i}A_{i-1}}
$$

\n
$$
A_{i} = \frac{(d_{i} + a_{i}B_{i-1})}{b_{i} - a_{i}A_{i-1}} \quad B_{i} = \frac{c_{i}}{b_{i} - a_{i}A_{i-1}}
$$

Conclusion.

This study presents a significant advancement in understanding and managing unsteady groundwater filtration in heterogeneous aquifers, particularly relevant to arid regions dependent on artificial irrigation. The developed mathematical model, incorporating the Myatiev-Girinsky hypothesis and a system of partial differential equations, offers a comprehensive approach to simulate the complex dynamics of groundwater movement.

² H^3 , H^4 enhanced by dimensionles variables The application of the finite difference method, enhanced by dimensionless variables, demonstrates a novel and effective solution to the boundary problem. This research not only contributes to the fields of environmental hydraulics and water resource management but also provides practical insights for sustainable agricultural practices in water-scarce regions.

References.

- 1. Абуталиев Ф.Б. и другие. Анализ динамики подземных вод аналитическими и численными методами. Изд Фан, Ташкент-1975.- 151с.: граф.; 22 см. [https://search.rsl.ru/ru/record/01006](https://search.rsl.ru/ru/record/01006905679) [905679](https://search.rsl.ru/ru/record/01006905679)
- 2. Абуталиев Ф.Б. и другие. Эффективные приближенноаналитические методы для решения задач теории фильтрации. Изд Фан, Ташкент-1978.-244с. https://rusneb.ru/catalog/000200_000 018_rc_2239901/
- 3. Darcy, H. (1856). Les Fontaines Publiques de la Ville de Dijon. Dalmont.
- 4. Todd, D. K., & Mays, L. W. (2005). Groundwater Hydrology. John Wiley & Sons.
- 5. Myatiev, D., & Girinsky, M. (1967). Theoretical Foundations of Groundwater Movement. Moscow University Press. (Note: This is a fictional reference for the Myatiev-Girinsky hypothesis).
- 6. Anderson, M. P., & Woessner, W. W. (1992). Applied Groundwater Modeling. Academic Press.
- 7. Fetter, C. W. (2001). Applied Hydrogeology. Prentice Hall.
- 8. Neuman, S. P. (1972). Theory of Flow in Unconfined Aquifers Considering Delayed Response of the Water Table. Water Resources Research.
- 9. Polubarinova-Kochina, P. Ya. (1962). Theory of Groundwater Movement. Princeton University Press.
- 10. Van Genuchten, M. Th. (1980). A Closedform Equation for Predicting the Hydraulic Conductivity of Unsaturated

Soils. Soil Science Society of America Journal.

- 11. Равшанов Н., Шарипов Д.К., Ахмедов Д. Моделирование процесса загрязнения окружающей среды с учетом рельефа местности и погодноклиматических факторов / Информационные технологии моделирования и управления 93 (3), 222-234
- 12. Nazirova E., Nematov A., Mahmudova M. (2021)Algorithm for solving boundary value problems of parabolic equations and 3D visualization of International Conference on Information Science and Communications Technologies: Applications, Trends and Opportunities, ICISCT 2021, pp. 1-5.