



# Indicators of Electricity Consumption in Asynchronous Motors Used in the Agricultural Industry

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**ABSTRACT**

In this article ways to achieve energy savings during the operation of an asynchronous electric motor are described. The method of using an asynchronous electric motor for the purpose of energy saving of electricity is described. Analysis of the energy saving potential that significant savings in electrical energy can be obtained by improving the efficiency of the asynchronous motor.

**Keywords:**

Induction motor power factor, active power, reactive power, apparent power, power factor load, power dependency to two polar generators

**Introduction.** As you know, the agrarian sector in our republic is improving and developing more and more. Three-phase asynchronous motors are the main consumers of electricity used in agricultural enterprises. 70-80% of the generated electricity is used in electric motors [1,2]. However, the main part of the main reactive power consumption in electric motors is in asynchronous motors. With this in mind, compensation and increase in the reactive value that exceeds the norm in asynchronous motors [3,4]. Therefore, during the operation of the feed grinding device, a number of measures should be taken to start the asynchronous motor of the device, as well as to stabilize the supply voltage [4,5]. At present, a large amount of reactive power is consumed in the process of using an induction motor, which is used on the example of one of

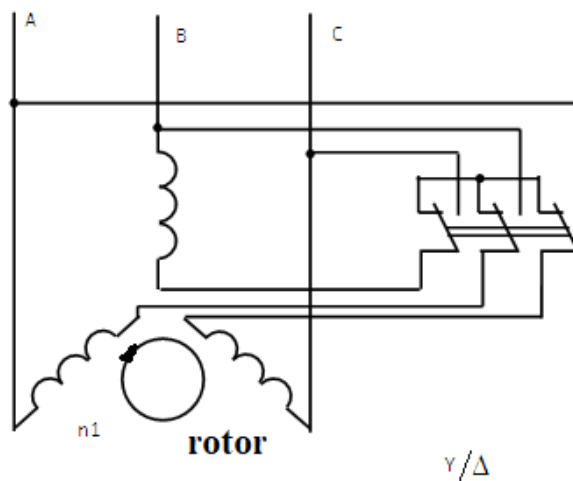
the agricultural enterprises "Research Institute of Agrotechnologies of Cotton Growing, Seed Growing, Bukhara". scientific and experimental station (PGUPATI Bukhara ITS)". At the same time, to increase the power factor of an asynchronous motor and reduce power losses in electrical equipment during operation of an asynchronous motor [6,7].

Currently, modern imported equipment and technologies are being introduced into the Republic of Uzbekistan, which must be provided with electricity in accordance with the requirements of European standards. Otherwise, this technique may not provide the expected quality and performance. Modern technological installations have an active feedback effect on the electrical network, and at the same time impose stringent requirements on the quality of electricity and

the reliability of solar power plants[8,9]. These circumstances require the reconstruction of enterprises, taking into account modern requirements, in particular, in terms of quality and efficiency in the use of electricity, automation of consumption, accounting, etc. Power loss in asynchronous motor are made up of losses in the stator (43.6%) and rotor (12.7%) windings, as well as power losses in the steel of magnetic systems asynchronous motor(43.7%). The total share of electrical and mechanical power losses in asynchronous motor account for 10.2% of active power consumption by motors[10,11].

**Method.** Total reactive power consumed asynchronous motor, consists of reactive powers due to the dissipation of stator (10.3%) and rotor (7.7%) windings asynchronous motor, and reactive power of magnetization circuits (82%). Reactive power consumed asynchronous motor. In asynchronous motors, when the voltage changes, the currents in the stator and

rotor windings and the magnetizing current of the motor change. Magnetizing losses increase with the square of the voltage. If the useful power given by the electric motor to the working body of an industrial installation is constant with a change in voltage, the losses in the stator and rotor vary inversely with the square of the voltage. Thus, the ratio of magnetization losses and electrical losses in the motor windings are different depending on the motor load: with a heavily loaded motor, the proportion of magnetization losses increases. In the total reactive power consumed asynchronous motor, a significant proportion is the reactive power of magnetization, proportional to the square of the mains voltage. Voltage reduction by 10% reactive power consumption asynchronous motor decreases by 12-14%. When the engine is underloaded, switching from the "delta" to the "star" circuit is recommended vice versa. [12,13]



**Fig.1. Connection diagram of the phases of the stator winding of an asynchronous motor**

This reduces the consumption of not only active power, but also reactive power. Energy savings is [14,15]:

$$\Delta W_s = (\Delta P + k\Delta Q) \cdot \Delta t;$$

(1)

Reducing power losses during the transition from the "triangle" to the "star" we have:

$$\Delta P_a = \frac{P}{\eta_\Delta} - \frac{P}{\eta_Y} = \frac{P}{\eta_\Delta} \cdot \left( \frac{\eta_Y - \eta_\Delta}{\eta_Y} \right); \text{ kVt};$$

(2)

reactive power reduction:

$$\Delta Q = \frac{P}{\eta_\Delta} \text{tg}\varphi_\Delta - \frac{P}{\eta_Y} \text{tg}\varphi_Y;$$

(3)

And the total active power savings:

$$\Delta P = k \cdot \Delta Q + \Delta P, \tag{4}$$

where: k-factor that determines the loss of active power corresponding to 1 kvar of reactive power, kW/kvar.

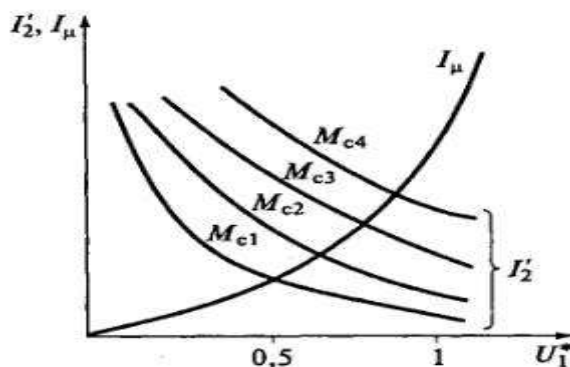
An effective means of energy saving in asynchronous electric drives is to reduce the voltage supplied to the motor during its operation with small loads or in idle mode. In this case, there is a decrease in the consumed reactive power and, thereby, losses in the elements of the power supply system. electric drive, and when op determined load factors - and power losses in the engine. The reactive power Q consumed by the asynchronous motor when using P-figurative scheme substitution is determined by the formula: [16,17]

$$Q = Q_{\Gamma\Pi} + Q_{\Pi P} = 3 \cdot U_1 \cdot I_{\mu} + 3 \cdot I_1^2 \cdot X_1 + 3 \cdot I_2^2 \cdot X'_2 = 3 \cdot \frac{U_1^2}{X_{\mu}} + 3 \cdot I_2^2 \cdot X_{k.3} = 3 \cdot \frac{U_1^2}{X_{\mu}} + M \cdot \omega_0 \cdot S \cdot \frac{X_{k.3}}{R'_2} \tag{5}$$

where Qgp, Qpr - reactive power, respectively, of the magnetic main field (GP) and magnetic

stray fields (PR) of the stator and rotor windings; U1 - voltage applied to the motor; Iμ, Xμ - respectively current and reactance of the magnetization circuit; I1 - stator current; I2 - reduced rotor current; X1, X2, Xk.z - inductive resistances, respectively, of the stator winding, reduced rotor winding and short circuit, Xk.z = X1+X2 M, ω0, S - respectively, the moment, idle speed and slip of the asynchronous motor. It follows from the expression that by reducing the voltage supplied to the motor, it is possible to influence the level of reactive power consumed by the motor and, thereby, the value of cosφ. This situation is illustrated by the dependences of the magnetization current Iμ and the reduced rotor current I2 on the motor supply voltage U1\* = U1/U1nom at different load moments Ms, shown in Fig.1.

It can be seen from Fig. 2 that a decrease in voltage leads to a decrease in the magnetizing current and, accordingly, in that part of the consumed reactive power that goes to create the main magnetic flux of the motor.



**Fig.2. Dependences of the magnetizing current and the reduced current of the rotor on the voltage on the stator**

At the same time, at a constant moment, the loads increase currents in circuits of the stator and rotor of the motor, which causes an increase in consumption reactive power used to create stray fields of the stator and rotor windings. Thus, voltage reduction can be carried out only at low motor loads or when it is idling, when the voltage reduction, which leads to a decrease in the motor magnetic flux, will not cause an increase in currents in the motor circuits [18,19]. For practical calculations, it is convenient to write the expression in the following form, which allows

taking into account the degree of load kn of the engine [1]:

$$Q = Q_0 + k_H^2 \cdot \Delta Q, \tag{6}$$

where Q0 - reactive power at idle speed of the engine; ΔQnom - increase in reactive power during the transition engine from idle to nominal.

The increase in reactive power is determined by the formula

$$\Delta Q_{\text{HOM}} = (Q_{\text{HOM}} - Q_0), \tag{7}$$

where Qnom - reactive power in nominal mode.

Reactive power in nominal mode is determined by the formula

$$P_{\text{HOM}} = 3 \cdot U_{\phi} \cdot I_{1\text{HOM}} \cdot \sin \varphi_{\text{HOM}} = P_{\text{HOM}} \cdot \frac{\tan \varphi_{\text{HOM}}}{\eta_{\text{HOM}}} \quad (8)$$

In practice, two ways to reduce the voltage have been applied: by switching the stator winding of the "triangle" circuit to the "star" circuit and by using thyristor voltage regulators. Consider the first of these methods. This method of voltage reduction is possible when the nominal phase voltage of the motor stator winding is equal to the line voltage of the network. At motor loads close to the nominal level, the stator windings are connected in a delta ( $\Delta$ ) and the motor operates at rated voltage with full magnetic flux. When the load decreases, the motor windings switch to the "star" (Y) circuit, a reduced voltage is supplied to the windings in  $\sqrt{3} = 1.73$  times the voltage, thereby reducing the magnetizing current, reactive power and total losses in the motor and system power supply. It is important to note that, in this case, the power losses in the engine, depending on its load factor, can

$$\Delta Q_{\Delta-Y} = Q_{\Delta} - \Delta Q_Y = 2 \cdot \frac{Q_0}{3} - 2 \cdot k_H^2 \cdot \Delta Q \quad (11)$$

as well as reducing power losses  $\Delta(\Delta P_{\Delta-Y})$  with this switching:

$$(9) \Delta P_{\Delta-Y} = \Delta P_{\Delta} - \Delta P_Y = 2 \cdot \frac{\Delta P_0}{3} - 2 \cdot k_H^2 \cdot \Delta P_{\text{HOM}} \quad (12)$$

An analysis of the ratio for the most probable values  $\Delta Q_0 = (0.60 \dots 0.75)$   $\Delta Q$  shows that with a load factor  $k_n < 0.7$ , the reactive power in the "star" circuit is always less than in the "triangle" circuit. Analysis of formula (5) with the most probable ratio  $\Delta P_0 \approx (0.30 \dots 0.35)$   $\Delta P_{\text{nom}}$  shows that the reduction of power losses in the engine during the transition to the "star" scheme will take place starting from the values of the engine load factor  $k_n < 0.4$ .

The formula for calculating the maximum possible relative load moment  $M^*$ s at  $k_u = 1/\sqrt{3}$ , which is typical when switching the stator windings from the "triangle" to the "star" circuit, at which the rotor current, power losses and heating do not exceed the nominal level:

$$M_c^* = \frac{(2 \cdot \lambda_M \cdot (\lambda_M + \sqrt{\lambda_M^2 - 1}) - 3)^{\frac{1}{2}}}{\sqrt{3} \cdot (\lambda_M + \sqrt{\lambda_M^2 - 1})} \quad (13)$$

both decrease as well as increase. The dependence of the reactive power of an induction motor on the voltage applied to the stator can be expressed by the formula [2].

$$Q \approx k_U^2 \cdot Q_0 + k_H^2 \cdot \frac{\Delta Q_{\text{HOM}}}{k_U^2},$$

(9)

where  $k_u$  is the voltage reduction factor equal to one when the stator windings are connected in a delta circuit and  $1/\sqrt{3}$  when the stator windings are connected in a star circuit [20,21].

The dependence of active power losses of an induction motor on the voltage applied to the stator can be expressed by a similar formula.

$$\Delta P \approx k_U^2 \cdot \Delta P_0 + k_H^2 \cdot \frac{\Delta P_{\text{HOM}}}{k_U^2},$$

(10)

where  $\Delta P_0$  is the power loss in the engine during idling, further taken to be equal to constant losses  $K$ .

Substituting in formulas (2) and (3) the values of  $k_u$  for both circuits, it is possible to determine the reduction in reactive power  $\Delta Q_{\Delta-Y}$  when switching windings:

In an asynchronous motor, when the stator windings are included in the "star" circuit, the motor, due to heating conditions, cannot carry a load of more than 60%. Consider an example of evaluating the economic efficiency of the considered method of energy saving.

**Results.** Determine the feasibility of the energy saving method in the electric drive by switching the motor windings 4A100S4U3, operating with a load factor  $k_n = 0.3$ , from the "triangle-nick" scheme to the "star" scheme. Rated motor data:  $P_{\text{nom}} = 30$  kW;  $U_{\text{nom}} = 220/380$  V;  $S_{\text{nom}} = 0.02$ ;  $I_{1\text{nom}} = 41.2$  A;  $\cos \varphi_{\text{nom}} = 0.85$ ;  $\sin \varphi_{\text{nom}} = 0.49$ ;  $\eta_{\text{nom}} = 90\%$ ;  $\lambda_m \setminus u003d M_k / M_{\text{nom}} \setminus u003d 2.2$ ;  $p = 3$ ;  $f_{1\text{nom}} = 50$  Hz.

- the operating time of the engine with the specified load factor per year is  $T_r = 1500$  h;

- the considered method of energy saving is implemented by creating a relay-contactor circuit for switching windings using four contactors.

- coefficient of depreciation deductions ka is taken in the amount of 10%;

- the tariff for electricity SE is 295 UZS / kWh (Uzbekistan, 2023).

We determine the ideal idle speed and the nominal angular velocity and moment:

$$\omega_0 = \frac{2 \cdot \pi \cdot f_1}{p} = 2 \cdot 3,14 \cdot \frac{50}{3} = 104,7 \text{ rad/s} \quad (14)$$

$$\omega_{\text{HOM}} = \omega_0 \cdot (1 - S_{\text{HOM}}) = 104,7 \cdot (1 - 0,02) = 103 \text{ rad/s} \quad (15)$$

$$M_{\text{HOM}} = \frac{P_{\text{HOM}}}{\omega_{\text{HOM}}} = \frac{30000}{103} = 291,3 \text{ Nm.} \quad (16)$$

Determine the nominal reduced current of the rotor:

$$I'_{2\text{HOM}} \approx I_{1\text{HOM}} \cdot \cos \varphi_{\text{HOM}} = 41,2 \cdot 0,85 = 48,5 \text{ A.} \quad (17)$$

We find the magnetizing current of the motor: Using the expression for the power loss in the rotor

$V_2 = I'^2_{2\text{HOM}} R'_2 = M \omega_0 S$ , written for the nominal mode, we find the reduced active resistance of the rotor: [source, page]

$$R'_2 = \frac{(M_{\text{HOM}} \cdot \omega_0 \cdot S_{\text{HOM}})}{3 \cdot I'^2_{2\text{HOM}}} = \frac{291,3 \cdot 104,7 \cdot 0,02}{3 \cdot 48,5^2} = \frac{609,9822}{7056,75} = 0,09 \text{ Om}$$

We calculate the reactive power in the nominal mode:

$$Q_{\text{HOM}} = 3 \cdot U_{\varphi} \cdot I_{1\text{HOM}} \cdot \sin \varphi_{\text{HOM}} = 3 \cdot 220 \cdot 41,2 \cdot 0,49 = 13324,08 \text{ var.}$$

We calculate the reactive power of idling:

$$Q_0 = m \cdot P_{\text{HOM}} / \eta_{\text{HOM}} = 0,31 \cdot \frac{30000}{0,90} =$$

$$10333 \text{ var,} \quad (18)$$

where  $m = 2.2 - 2.1 \cos \varphi_{\text{nom}} = 2.2 - 2.1 \cdot 0.85 = 0.415$ .

From the expression for the rated reactive power

$$Q_{\text{HOM}} = 3 \cdot U_{\varphi} \cdot I_{\mu} + M_{\text{HOM}} \cdot \omega_0 \cdot S_{\text{HOM}} \cdot \frac{X_{\text{K.3}}}{R'_2} =$$

$$Q_0 + \Delta Q_{\text{HOM}} \quad (19)$$

find Hk.Z:

$$X_{\text{K.3}} = R'_2 \cdot \frac{(Q_{\text{HOM}} - Q_0)}{M_{\text{HOM}} \cdot \omega_0 \cdot S_{\text{HOM}}} = 0,09 \cdot \frac{(13324,08 - 10333)}{(291,3 \cdot 104,7 \cdot 0,02)} = 0,09 \cdot \frac{2991,08}{609,9822} = 0,44 \text{ Om.}$$

We determine the active resistance of the stator circuit using formula for critical moment asynchronous motor:

$$M_K = 3 \cdot U_{\varphi}^2 / 2 \cdot \omega_0 \cdot (R_1 + \sqrt{R_1^2 + X_{\text{K.3}}^2}).$$

Expressing R1 from it as the desired value, we find: [5]

$$R_1 = \left( \frac{3 \cdot U_{\varphi}^2}{2 \cdot \omega_0 \cdot M_K} - X_{\text{K.3}}^2 \right) / \left( 2 \cdot \left( 3 \cdot \frac{U_{\varphi}^2}{2 \cdot \omega_0 \cdot M_K} \right) \right) = \left( \frac{3 \cdot 220^2}{2 \cdot 104,7 \cdot 2,2 \cdot 213,6} - 0,44^2 \right) / \left( 2 \cdot \left( \frac{3 \cdot 220^2}{2 \cdot 104,7 \cdot 2,2 \cdot 213,6} \right) \right) = \frac{\left( \frac{145200}{98401,248} - 0,1936 \right)}{\left( 2 \cdot \left( \frac{145200}{98401,248} \right) \right)} = \frac{1,9968}{2,9512}$$

$$= 0,68 \text{ Om}$$

Determine the total nominal losses:

$$\Delta P_{\text{HOM}} = \frac{P_{\text{HOM}} \cdot (1 - \eta_{\text{HOM}})}{\eta_{\text{HOM}}} = \frac{30000 \cdot (1 - 0,82)}{0,82} = \frac{5400}{0,82} = 6585 \text{ Vt}$$

We find variable nominal losses:

$$V_{\text{HOM}} = V_{1\text{HOM}} + V_{2\text{HOM}} = 3 \cdot I_{1\text{HOM}}^2 \cdot R_1 + 3 \cdot I'^2_{2\text{HOM}} \cdot R'_2 = 3 \cdot 41,2^2 \cdot 0,68 + 3 \cdot 48,5^2 \cdot 0,04 = 3462,7776 + 282,27 = 3745 \text{ Vt.}$$

Finding permanent power losses

$$K = \Delta P_{\text{HOM}} - V_{\text{HOM}} = 6585 - 3745 = 2840 \text{ Vt.}$$

We calculate by formula (8) the decrease in reactive power  $\Delta Q_{\Delta-Y}$  when switching the stator windings from the "triangle" circuit to the "star" circuit:

$$\Delta Q_{\Delta-Y} = \Delta Q_{\Delta} - \Delta Q_Y = 2 \cdot \frac{\Delta Q_0}{3} - 2 \cdot k_H^2 \cdot$$

$$\Delta Q_{\text{HOM}} = 2 \cdot \frac{8261}{3} - 2 \cdot 0,3^2 \cdot$$

$$13324,08 = 5507,2864 - 2398,3344 = 3109 \text{ var.}$$

Using formula (9), we calculate the reduction in active power  $\Delta (\Delta P_{\Delta-Y})$  when switching the stator windings from the "triangle" circuit to the "star" circuit

$$\Delta(\Delta P_{\Delta-Y}) = \Delta P_{\Delta} - \Delta P_Y = 2 \cdot \frac{\Delta P_0}{3} - 2 \cdot k_H^2 \cdot \Delta P_{\text{НОМ}} = 2 \cdot \frac{2107}{3} - 2 \cdot 0,3^2 \cdot 6585 = 1404,7 - 1185,3 = 219 \text{ Vt.}$$

The total reduction in power losses will be

$$\Delta P_{\text{ЭК}} = k_H \cdot \Delta Q_{\Delta-Y} + \Delta \cdot (\Delta P_{\Delta-Y}) = 0,1 \cdot 4490 + 219 = 668 \text{ Vt,}$$

where  $k_H$  is the coefficient of power loss reduction obtained from the reduction of reactive power  $Q$ , kW/kvar.

Payback time The current is determined by the formula

$$\begin{aligned} & T_{\text{ОК}} \\ &= \frac{C_{\text{КОИТ}} \cdot (T_p \cdot C_{\text{Э}} \cdot \Delta P_{\text{ЭК}} - p_a C_{\text{КОИТ}})}{1,6 \cdot 4 \cdot 2022} = \\ &= \frac{1500 \cdot 295 \cdot 0.668 - 0,1 \cdot 4 \cdot 2022}{12940,8} = \frac{12940,8}{295590 - 808,8} = \frac{12940,8}{294781,2} = 0,04 \text{ y.} \end{aligned}$$

### Discussion and conclusions:

Theoretical calculations and experimental data show that in the case of the enterprise "Research Institute of Agrotechnologies for Breeding, Seed Production of Cotton at the Bukhara Research and Experimental Station (NPGUAIT Bukhara ITS)", when an asynchronous motor is running, connecting the coils of an asynchronous motor, connecting electricity according to the triangle-star scheme reduces losses by a few percent, which saves electricity for an asynchronous motor.

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